# Machine Learning

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# Chapter 7: Support Vector Machines and Kernels

$$R[f_n] \leq R_{\mathsf{emp}}[f_n] + \sqrt{rac{a}{n}} \left( \mathsf{capacity}(\mathcal{H}) + \mathsf{ln} \ rac{b}{\delta} 
ight)$$

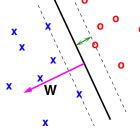
- $\rightsquigarrow$  minimizing capacity( $\mathcal{H}$ ) corresponds to maximizing the margin.
- → Large margin classifiers.

#### **SVMs**

• When the training examples are **linearly separable** we can maximize the margin by minimizing the regularization term

$$\|\mathbf{w}\|^2/2 = \sum_{i=1}^d w_i^2/2$$

subject to the **classification constraints**  $y_i[\mathbf{x}_i^t \mathbf{w}] - 1 > 0, i = 1, ..., n.$ 



 The solution is defined only on the basis of a subset of examples or support vectors.

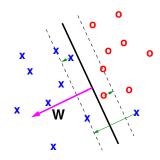
# SVMs: nonseparable case

Modify optimization problem slightly by adding a **penalty for violating the classification constraints:** 

$$\text{minimize} \ \| \boldsymbol{w} \|^2 / 2 + C \sum_{i=1}^n \xi_i$$

subject to relaxed constraints

$$y_i[\mathbf{x}_i^t \mathbf{w}] - 1 + \xi_i \ge 0, \ i = 1, ..., n.$$



• The  $\xi_i \geq 0$  are called **slack variables**.

# SVMs: nonseparable case

We can also write the SVM optimization problem more compactly as

$$C\sum_{i=1}^{n} \overbrace{(1-y_i[\boldsymbol{x}_i^t\boldsymbol{w}])^+}^{\xi_i} + \|\boldsymbol{w}\|^2/2,$$

where  $(z)^+ = z$  if  $z \ge 0$  and zero otherwise.

• This is equivalent to regularized empirical loss minimization

$$\underbrace{\frac{1}{n} \sum_{i=1}^{n} (1 - y_i[\boldsymbol{x}_i^t \boldsymbol{w}])^+ + \lambda \|\boldsymbol{w}\|^2}_{R_{\text{core}}},$$

where  $\lambda = 1/(2nC)$  is the regularization parameter.

#### SVMs and LOGREG

 When viewed from the point of view of regularized empirical loss minimization, SVM and logistic regression appear quite similar:

SVM: 
$$\frac{1}{n} \sum_{i=1}^{n} (1 - y_i [\mathbf{x}_i^t \mathbf{w}])^+ + \lambda ||\mathbf{w}||^2$$

LOGREG: 
$$\frac{1}{n} \sum_{i=1}^{n} -\log \overbrace{\sigma(y_{i}[\mathbf{x}_{i}^{t}\mathbf{w}])}^{P(y_{i}|\mathbf{x}_{i},\mathbf{w})} + \lambda \|\mathbf{w}\|^{2},$$

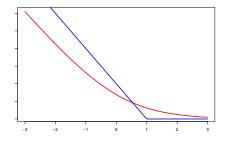
where  $\sigma(z) = (1 + e^{-z})^{-1}$  is the logistic function.

#### SVMs and LOGREG

• The difference comes from how we penalize errors:

Both: 
$$\frac{1}{n} \sum_{i=1}^{n} \text{Loss}(y_i[\mathbf{x}_i^t \mathbf{w}]) + \lambda \|\mathbf{w}\|^2$$
,

- SVM: Loss $(z) = (1 z)^+$
- LOGREG: Loss(z) = log(1 + exp(-z))



# SVMs: solution, Lagrange multipliers

• Back to the separable case: how do we solve

minimize<sub>w</sub> 
$$\|\mathbf{w}\|^2/2$$
 s.t.  $y_i[\mathbf{x}_i^t\mathbf{w}] - 1 \ge 0$ ,  $i = 1, ..., n$ .

• Represent the constraints as individual loss terms:

$$\sup_{\alpha_i \geq 0} \alpha_i (1 - y_i[\mathbf{x}_i^t \mathbf{w}]) = \begin{cases} 0, & \text{if } y_i[\mathbf{x}_i^t \mathbf{w}] - 1 \geq 0, \\ \infty, & \text{otherwise.} \end{cases}$$

• Rewrite the minimization problem:

$$\begin{aligned} & \text{minimize}_{\boldsymbol{w}} & \|\boldsymbol{w}\|^2/2 + \sum_{i=1}^n \sup_{\alpha_i \geq 0} \alpha_i (1 - y_i[\boldsymbol{x}_i^t \boldsymbol{w}]) \\ &= \text{minimize}_{\boldsymbol{w}} & \sup_{\alpha_i \geq 0} \left( \|\boldsymbol{w}\|^2/2 + \sum_{i=1}^n \alpha_i (1 - y_i[\boldsymbol{x}_i^t \boldsymbol{w}]) \right) \end{aligned}$$

# SVMs: solution, Lagrange multipliers

 Swap maximization and minimization (technically this requires that the problem is convex and feasible 
 Slater's condition):

$$\begin{aligned} & \operatorname{minimize}_{\boldsymbol{w}} & \left[ \sup_{\alpha_i \geq 0} \left( \| \boldsymbol{w} \|^2 / 2 + \sum_{i=1}^n \alpha_i (1 - y_i [\boldsymbol{x}_i^t \boldsymbol{w}]) \right) \right] \\ &= \operatorname{maximize}_{\alpha_i \geq 0} & \left[ \min_{\boldsymbol{w}} \left( \| \boldsymbol{w} \|^2 / 2 + \sum_{i=1}^n \alpha_i (1 - y_i [\boldsymbol{x}_i^t \boldsymbol{w}]) \right) \right] \\ & \underbrace{ \int_{J(\boldsymbol{w};\alpha)}} & \underbrace{J(\boldsymbol{w};\alpha)} & \underbrace{ \int_{J(\boldsymbol{w};\alpha)}} & \underbrace{ \int_{J(\boldsymbol{w};\alpha)}} & \underbrace{ \int_{J(\boldsymbol{w}$$

• We have to minimize  $J(w; \alpha)$  over parameters w for fixed Lagrange multipliers  $\alpha_i \geq 0$ .

Simple, because  $J(\mathbf{w})$  is convex  $\rightsquigarrow$  set derivative to zero  $\rightsquigarrow$  only one stationary point  $\rightsquigarrow$  global minimum.

## SVMs: solution, Lagrange multipliers

• Find optimal **w** by setting the derivatives to zero:

$$\frac{\partial}{\partial \mathbf{w}} J(\mathbf{w}; \boldsymbol{\alpha}) = \mathbf{w} - \sum_{i} \alpha_{i} y_{i} \mathbf{x}_{i} = 0 \implies \hat{\mathbf{w}} = \sum_{i} \alpha_{i} y_{i} \mathbf{x}_{i}.$$

 Substitute the solution back into the objective and get (after some re-arrangements of terms):

$$\max_{\alpha_i \geq 0} \min_{\mathbf{w}} \left( \|\mathbf{w}\|^2 / 2 + \sum_{i=1}^n \alpha_i (1 - y_i [\mathbf{x}_i^t \mathbf{w}]) \right)$$

$$= \max_{\alpha_i \geq 0} \left( \|\hat{\mathbf{w}}\|^2 / 2 + \sum_{i=1}^n \alpha_i (1 - y_i [\mathbf{x}_i^t \hat{\mathbf{w}}]) \right)$$

$$= \max_{\alpha_i \geq 0} \left( \sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i,j=1}^n y_i y_j \alpha_i \alpha_j \mathbf{x}_i^t \mathbf{x}_j \right)$$

## SVMs: summary

• Find optimal Lagrange multipliers  $\hat{\alpha}_i$  by maximizing

$$\sum_{i=1}^{n} \alpha_i - \frac{1}{2} \sum_{i,j=1}^{n} y_i y_j \alpha_i \alpha_j \boldsymbol{x}_i^t \boldsymbol{x}_j \quad \text{ subject to } \alpha_i \geq 0.$$

- Only  $\hat{\alpha}_i$ 's corresponding to **support vectors** will be non-zero.
- $\bullet$  Make **predictions** on any new example x according to:

$$\operatorname{sign}(\mathbf{x}^t \hat{\mathbf{w}}) = \operatorname{sign}(\mathbf{x}^t \sum_{i=1}^n \hat{\alpha}_i y_i \mathbf{x}_i) = \operatorname{sign}(\sum_{i \in SV} \hat{\alpha}_i y_i \mathbf{x}^t \mathbf{x}_i).$$

- Observation: dependency on input vectors only via dot products.
- Later we will introduce the **kernel trick** for efficiently computing these dot products in implicitly defined feature spaces.

#### SVMs: formal derivation

Convex optimization problem: an optimization problem

minimize 
$$f(x)$$
 (1)

subject to 
$$g_i(\mathbf{x}) \leq 0, \quad i = 1, \dots, m$$
 (2)

is convex if the functions  $f, g_1 \dots g_m : \mathbb{R}^n \to \mathbb{R}$  are convex.

• The Lagrangian function for the problem is

$$\mathcal{L}(\mathbf{x},\lambda_0,...,\lambda_m) = \lambda_0 f(\mathbf{x}) + \lambda_1 g_1(\mathbf{x}) + ... + \lambda_m g_m(\mathbf{x}).$$

- Karush-Kuhn-Tucker (KKT) conditions: For each point  $\hat{x}$  that minimizes f, there exist real numbers  $\lambda_0, \ldots, \lambda_m$ , called **Lagrange multipliers**, that simultaneously satisfy:
  - ①  $\hat{\mathbf{x}}$  minimizes  $\mathcal{L}(\mathbf{x}, \lambda_0, \lambda_1, \dots, \lambda_m)$ ,
  - ②  $\lambda_0 \geq 0, \lambda_1 \geq 0, \dots, \lambda_m \geq 0$ , with at least one  $\lambda_k > 0$ ,
  - **3** Complementary slackness:  $g_i(\hat{\mathbf{x}}) < 0 \Rightarrow \lambda_i = 0$ ,  $1 \le i \le m$ .

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### SVMs: formal derivation

- Slater's condition: If there exists a strictly feasible point z satisfying  $g_1(z) < 0, \ldots, g_m(z) < 0$ , then one can set  $\lambda_0 = 1$ .
- Assume that Slater's condition holds. Minimizing the supremum  $\mathcal{L}^*(\mathbf{x}) = \sup_{\lambda > 0} \mathcal{L}(\mathbf{x}, \lambda)$ , is the **primal problem P**:

$$\hat{\mathbf{x}} = \operatorname*{argmin}_{\mathbf{x}} \mathcal{L}^*(\mathbf{x}).$$

Note that

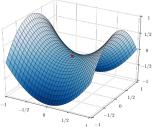
$$\mathcal{L}^*(\mathbf{x}) = \sup_{\lambda \ge 0} \left( f(\mathbf{x}) + \sum_{i=1}^m \lambda_i g_i(\mathbf{x}) \right) = \begin{cases} f(\mathbf{x}) & \text{, if } g_i(\mathbf{x}) \le 0 \,\forall i \\ \infty & \text{, else.} \end{cases}$$

- $\rightsquigarrow$  Minimizing  $\mathcal{L}^*(x)$  is equivalent to minimizing f(x).
- The maximizer of the dual problem D is

$$\hat{\pmb{\lambda}} = \mathop{\mathsf{argmax}}_{\pmb{\lambda}} \mathcal{L}_*(\pmb{\lambda}), \ \ \mathsf{where} \ \mathcal{L}_*(\pmb{\lambda}) = \inf_{\pmb{x}} \mathcal{L}(\pmb{x}, \pmb{\lambda}).$$

#### SVMs: formal derivation

- The non-negative number min(P) max(D) is the **duality gap.**
- Convexity and Slater's condition imply strong duality:
  - The optimal solution  $(\hat{x}, \hat{\lambda})$  is a saddle point of  $\mathcal{L}(x, \lambda)$
  - 2 The duality gap is zero.
- Discussion: For any real function f(a, b) min<sub>a</sub>[max<sub>b</sub> f(a, b)] ≥ max<sub>b</sub>[min<sub>a</sub> f(a, b)].
   Equality → saddle value exists.



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#### Kernel functions

- A **kernel function** is a real-valued function of two arguments,  $k(\mathbf{x}, \mathbf{x}') \in \mathbb{R}$ , for  $\mathbf{x}, \mathbf{x}' \in \mathcal{X}$ .
- Typically the function is **symmetric**, and sometimes non-negative.
- In the latter case, it might be interpreted as a measure of similarity.
- Example: isotropic Gaussian kernel:

$$k(\mathbf{x}, \mathbf{x}') = \exp\left(-\frac{\|\mathbf{x} - \mathbf{x}'\|^2}{2\sigma^2}\right)$$

Here,  $\sigma^2$  is the bandwidth. This is an example of a radial basis function (RBF) kernel (only a function of  $\|x - x'\|^2$ ).

#### Mercer kernels

• A symmetric kernel is a **Mercer kernel**, iff the Gram matrix

$$K = \begin{pmatrix} k(\mathbf{x}_1, \mathbf{x}_1) & \dots & k(\mathbf{x}_1, \mathbf{x}_n) \\ \vdots & & \vdots \\ k(\mathbf{x}_n, \mathbf{x}_1) & \dots & k(\mathbf{x}_n, \mathbf{x}_n) \end{pmatrix}$$

is **positive semidefinite** for any set of inputs  $\{x_i, \ldots, x_n\}$ .

• Mercer's theorem: Eigenvector decomposition

$$K = V\Lambda V^t = (V\Lambda^{1/2})(V\Lambda^{1/2})^t =: \Phi\Phi^t.$$

Eigenvectors: columns of V. Eigenvalues: entries of diagonal matrix  $\Lambda = \operatorname{diag}(\lambda_1,\ldots,\lambda_n)$ . Note that  $\lambda_i \in \mathbb{R}$  and  $\lambda_i \geq 0$ . Define  $\phi(\mathbf{x}_i)^t = i$ -th row of  $\Phi = V_{[i\bullet]}\Lambda^{1/2}$ 

$$\rightsquigarrow k(\mathbf{x}_i, \mathbf{x}_{i'}) = \phi(\mathbf{x}_i)^t \phi(\mathbf{x}_{i'}).$$

 Entries of K: inner product of some feature vectors, implicitly defined by eigenvectors V.

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#### Mercer kernels

• If the kernel is **Mercer**, then there exists  $\phi: \mathbf{x} \to \mathbb{R}^d$  such that  $k(\mathbf{x}, \mathbf{x}') = \phi(\mathbf{x})^t \phi(\mathbf{x}')$ .

where  $\phi$  depends on the eigenfunctions of k (d might be infinite).

• Example: Polynomial kernel

$$k(\mathbf{x}, \mathbf{x}') = (1 + \mathbf{x}^t \mathbf{x}')^m.$$

Corresponding feature vector contains terms up to degree m.

Example:  $m = 2, x \in \mathbb{R}^2$ :

$$(1 + \mathbf{x}^t \mathbf{x}')^2 = 1 + 2x_1 x_1' + 2x_2 x_2' + (x_1 x_1')^2 + (x_2 x_2')^2 + 2x_1 x_1' x_2 x_2'.$$

Thus,

$$\phi(\mathbf{x}) = [1, \sqrt{2}x_1, \sqrt{2}x_2, x_1^2, x_2^2, \sqrt{2}x_1x_2]^t.$$

Equivalent to working in a 6-dim feature space.

• Gaussian kernel: feature map lives in an infinite dimensional space.

#### Kernels for documents

- In document classification or retrieval, we want to compare two documents, x<sub>i</sub> and x<sub>i'</sub>.
- Bag of words representation:
   x<sub>ij</sub> is the number of times word j occurs in document i.
- One possible choice: **Cosine similarity:**

$$k(\mathbf{x}_i, \mathbf{x}_{i'}) = \frac{\mathbf{x}_i^{\mathsf{t}} \mathbf{x}_{i'}}{\|\mathbf{x}_i\| \|\mathbf{x}_{i'}\|} =: \phi(\mathbf{x}_i)^{\mathsf{t}} \phi(\mathbf{x}_{i'}).$$

- Problems:

  - Bias: once a word is used in a document, it is very likely to be used again.
- Solution: Replace word counts with "normalized" representation.

#### Kernels for documents

TF-IDF "term frequency inverse document frequency":

**Term frequency** is log-transform of the count:

$$\mathsf{tf}(x_{ij}) = \mathsf{log}(1 + x_{ij})$$

#### Inverse document frequency:

$$idf(j) = log \frac{\#(documents)}{\#(documents containing term j)} = log \frac{1}{\hat{p}_i}.$$

→ Shannon information content:

#### idf is a measure of how much information a word provides

• Combine with tf → counts weighted by information content:

$$\mathsf{tf}\text{-}\mathsf{idf}(\boldsymbol{x}_i) = [\mathsf{tf}(\boldsymbol{x}_{ij}) \cdot \mathsf{idf}(j)]_{j=1}^V, \text{ where } V = \mathsf{size} \text{ of vocabulary.}$$

• We then use this inside the **cosine similarity measure**. With  $\phi(x) = \text{tf-idf}(x)$ :

$$k(\mathbf{x}_i,\mathbf{x}_{i'}) = \frac{\phi(\mathbf{x}_i)^t \phi(\mathbf{x}_{i'})}{\|\phi(\mathbf{x}_i)\| \|\phi(\mathbf{x}_{i'})\|}.$$



## String kernels

- Real power of kernels arises for structured input objects.
- Consider two strings x, and x' of lengths d, d', over alphabet A. Idea: define similarity as the **number of common substrings**.
- If s is a substring of  $x \rightsquigarrow \phi_s(x) = \text{number of times } s \text{ appears in } x$ .
- String kernel

$$k(x,x') = \sum_{s \in A^*} w_s \phi_s(x) \phi_s(x'),$$

where  $w_s \geq 0$  and  $\mathcal{A}^* = \text{set of all strings (any length) from } \mathcal{A}$ .

- One can show: Mercer kernel, can be computed in O(|x| + |x'|) time using suffix trees (Shawe-Taylor and Cristianini, 2004).
- Special case:  $w_s = 0$  for |s| > 1: **bag-of-characters kernel:**  $\phi(x)$  is the number of times each character in  $\mathcal{A}$  occurs in x.

#### The kernel trick

- Idea: modify algorithm so that it **replaces all inner products**  $x^t x'$  with a call to the **kernel function** k(x, x').
- **Kernelized ridge regression:**  $\hat{\boldsymbol{w}} = (X^t X + \lambda I)^{-1} X^t \boldsymbol{y}$ . Matrix inversion lemma:

$$(I + UV)^{-1}U = U(I + VU)^{-1}$$

Define new variables  $\alpha_i$ :

$$\hat{\boldsymbol{w}} = (X^t X + \lambda I)^{-1} X^t \boldsymbol{y}$$

$$= X^t \underbrace{(XX^t + \lambda I)^{-1} \boldsymbol{y}}_{\hat{\alpha}} = \sum_{i=1}^n \hat{\alpha}_i \boldsymbol{x}_i.$$

 $\rightarrow$  solution is linear sum of the *n* training vectors.

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#### The kernel trick

• Use this and the kernel trick to make **predictions for** x:

$$\hat{f}(\mathbf{x}) = \hat{\mathbf{w}}^t \mathbf{x} = \sum_{i=1}^n \hat{\alpha}_i \mathbf{x}_i^t \mathbf{x} = \sum_{i=1}^n \hat{\alpha}_i k(\mathbf{x}_i, \mathbf{x}).$$

Same for SVMs:

$$\hat{\boldsymbol{w}}^t \boldsymbol{x} = \sum_{i \in SV} \hat{\alpha}_i y_i \boldsymbol{x}_i^t \boldsymbol{x} = \sum_{i \in SV} \hat{\alpha}_i' k(\boldsymbol{x}_i, \boldsymbol{x})$$

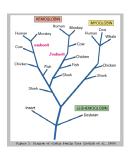
...and for most other classical algorithms in ML!

## Some applications in bioinformatics

Bioinformatics: often non-vectorial data-types:



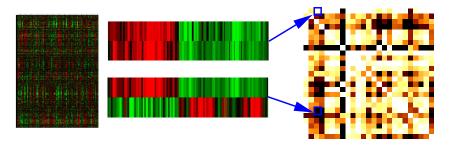
interaction graphs



- phylogenetic trees
- strings GSAQVKGHGKKVADALTNAVAHV
- Data fusion: convert data of each type into kernel matrix
  - **⇒** fuse kernel matrices
  - $\Rightarrow$  "common language" for heterogeneous data.

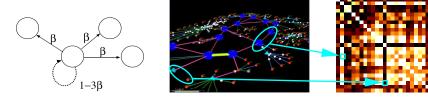
## RBF kernels from expression data

- Measurements (for each gene): vector of expression values under different experimental conditions
- "classical" RBF kernel  $k(x_1, x_2) = \exp(-\sigma ||x_1 x_2||^2)$



# Diffusion kernels from interaction-graphs

- A: Adjacency matrix, D: node degrees, L = D A.
- $K := \frac{1}{Z(\beta)} \exp(-\beta L)$  with transition probabilities  $\beta$ .
- Physical interpretation (random walk): randomly choose next node among neighbors.
- Self-transition occurs with prob.  $1 d_i \beta$



•  $K_{ij}$ : prob. for walk from i to j.

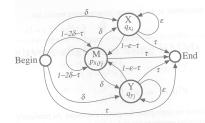
(Kondor and Lafferty, 2002)

## Alignment kernels from sequences

# Alignment with **Pair HMMs**→ Mercer kernel (Watkins, 2000).

Image source: Durbin, Eddy, Krogh, Mitchison. Biological Se-

quence Alignment. Cambridge.



HBA\_HUMAN GSAQVKGHGKKVADALTNAVAHV---D--DMPNALSALSDLHAHKL
++ ++++++ KV + +A ++ +L+ L+++++ K
LGB2 LUPLU NNPELOAHAGKVFKLVYEAAIOLOVTGVVVTDATLKNLGSVHVSKG



## Combination of heterogeneous data

#### Adding kernels ⇒ new kernel:

$$k_{1}(x,y) = \phi_{1}(x) \cdot \phi_{1}(y), k_{2}(x,y) = \phi_{2}(x) \cdot \phi_{2}(y)$$
  $\Rightarrow k' = k_{1} + k_{2} = \begin{pmatrix} \phi_{1}(x) \\ \phi_{2}(x) \end{pmatrix} \cdot \begin{pmatrix} \phi_{1}(y) \\ \phi_{2}(y) \end{pmatrix}$ 

Fusion & relevance determination: kernel-combinations

